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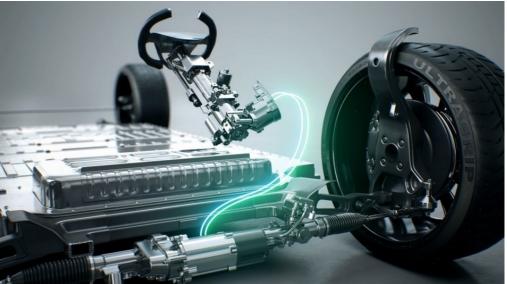
Optimizing Software-based Soft-Error Detector Configurations

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Motivation





• Hardware is effected by cosmic rays

- Isolation not always possible
- Redundant Hardware is expensive

→ Software-based hardware fault tolerance



Assertions for Fault Tolerance

- Assertion triggers if defined fault state occurs
 - Assertions (usually) deactivated in production
- Improve fault tolerance with existing assertions
- High number of assertions in most operating systems
 - e.g. tens of thousands for the Linux Kernel

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static int dbFindLeaf(dmtree_t * tp, int l2nb, int *leafidx)
{

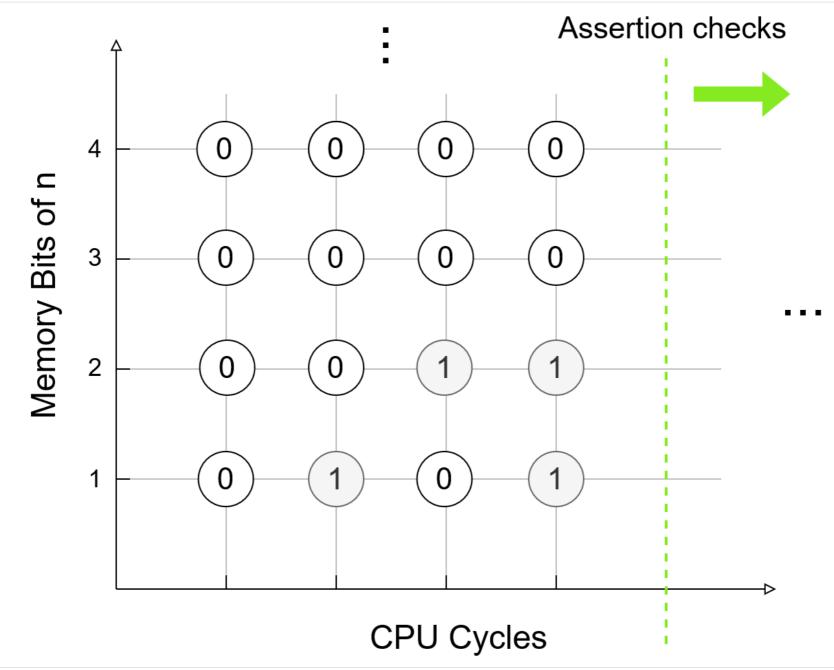
```
int ti, n = 0, k, x = 0;
```

```
if (l2nb > tp->dmt_stree[ROOT])
return -ENOSPC;
```

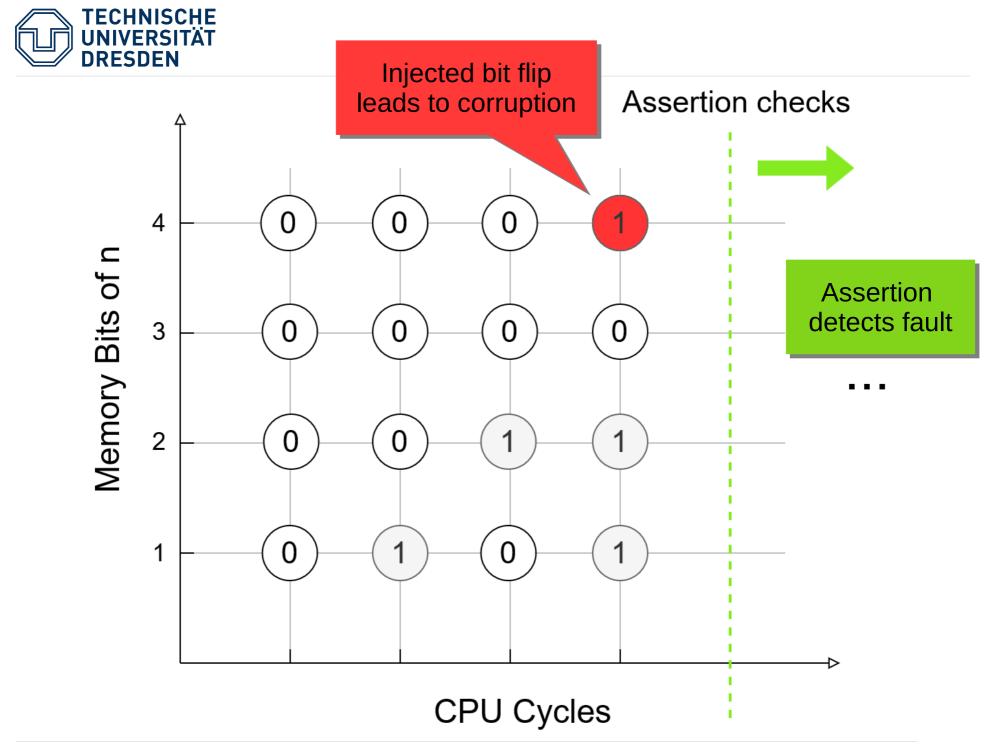
```
for (k = le32_to_cpu(tp->dmt_height), ti = 1;
k > 0; k--, ti = ((ti + n) << 2) + 1) {</pre>
```

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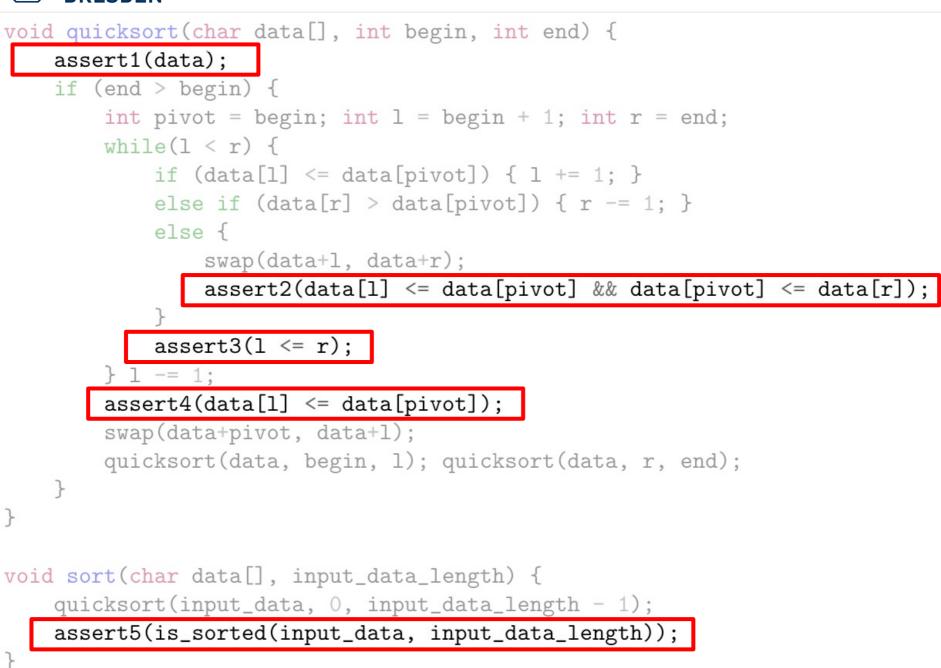


Assertions for Fault Tolerance



Assertions for Fault Tolerance







Are all assertions positive for fault tolerance?



| assert1 | assert2 | assert3 | assert4 | assert5 | SDC count | |
|---------|---------|---------|---------|---------|-----------|-----|
| 0 | 0 | 0 | 0 | 1 | 667 792 | |
| 1 | 0 | 0 | 0 | 1 | 688 507 | |
| 0 | 1 | 0 | 0 | 1 | 697 033 | |
| 0 | 0 | 0 | 1 | 1 | 701 957 | 11% |
| 0 | 0 | 1 | 0 | 1 | 703 802 | 56% |
| | | | : | | | |
| 1 | 1 | 1 | 1 | 1 | 755 252 | |
| | | | : | | | |
| 0 | 0 | 0 | 0 | 0 | 1 539 162 | |

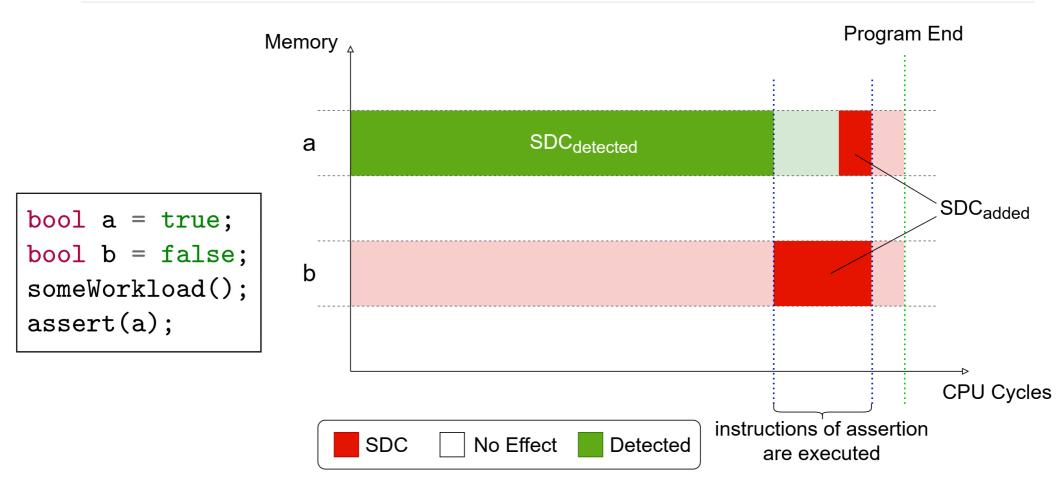


```
void quicksort(char data[], int begin, int end) {
  -assert1(data);
    if (end > begin) {
        int pivot = begin; int l = begin + 1; int r = end;
        while (1 < r) {
            if (data[1] <= data[pivot]) { 1 += 1; }
            else if (data[r] > data[pivot]) { r -= 1; }
            else {
                swap(data+1, data+r);
               -assert2(data[1] <= data[pivot] && data[pivot] <= data[r]);</pre>
           -assert3(1 <= r);
        \} 1 -= 1;
        assert4(data[l] <= data[pivot]);</pre>
        swap(data+pivot, data+l);
        quicksort(data, begin, 1); quicksort(data, r, end);
    }
}
void sort(char data[], input_data_length) {
    quicksort(input_data, 0, input_data_length - 1);
    assert5(is_sorted(input_data, input_data_length));
```



Why are certain assertions bad for fault tolerance?

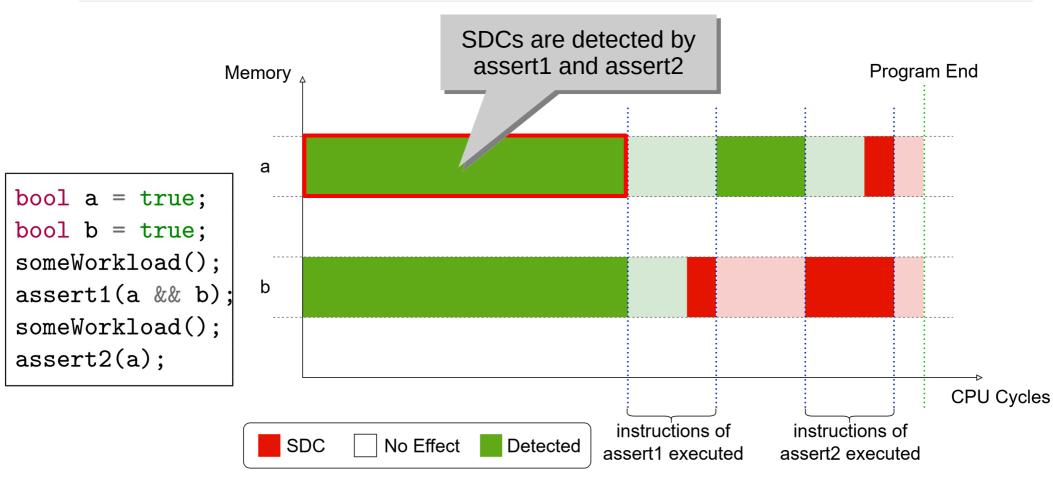




- Runtime of assertion increases attack surface
- Total number of reduced SDCs is determined by

SDC_{detected} - SDC_{added}





- assert1 and assert2 detects partly the same SDCs
- Assertions are not independent from each other

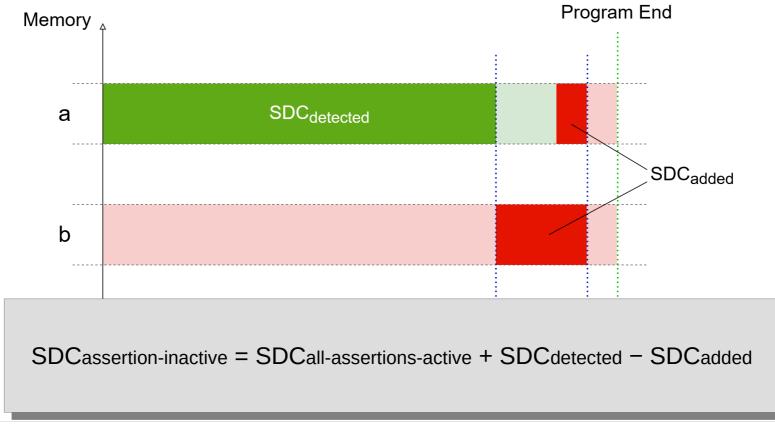


How to choose the optimal selection out of N assertions?



Finding an Optimal Configuration

- Executing all 2^N configurations practically not possible
- Calculate SDCs of configuration from fault injection campaign with all assertions active



Optimal Selection



| assert1 | assert2 | assert3 | assert4 | assert5 | SDC real | SDC synthetic | error |
|---------|---------|---------|---------|---------|-----------|------------------|--------|
| 0 | 0 | 0 | 0 | 1 | 667 792 | 671 174 | 0.50% |
| 1 | 0 | 0 | 0 | 1 | 688 507 | 680 590 | -1.16% |
| 0 | 1 | 0 | 0 | 1 | 697 033 | 696 201 | -0.12% |
| 0 | 0 | 0 | 1 | 1 | 701 957 | 693 018 | -1.29% |
| 0 | 0 | 1 | 0 | 1 | 703 802 | 698 904 | -0.70% |
| | | | | ÷ | | | |
| 1 | 1 | 1 | 1 | 1 | 755 252 | 755 252 | 0.00% |
| | | | | ÷ | | | |
| 0 | 0 | 0 | 0 | 0 | 1 539 162 | 1 569 759 | 1.95% |



Finding an Optimal Configuration

Calculating all 2^N configurations may be still not possible

Integer Linear Programming could be the salvation

- Minimize cost function under linear constraints
- Addition and subtraction of detected and added SDCs
- Existing ILP solver like glpsol or gurobi can be used



Evaluation

FreeRTOS

- 224 assertions in code
- Demo with mutex and queue
- 60 assertions executed

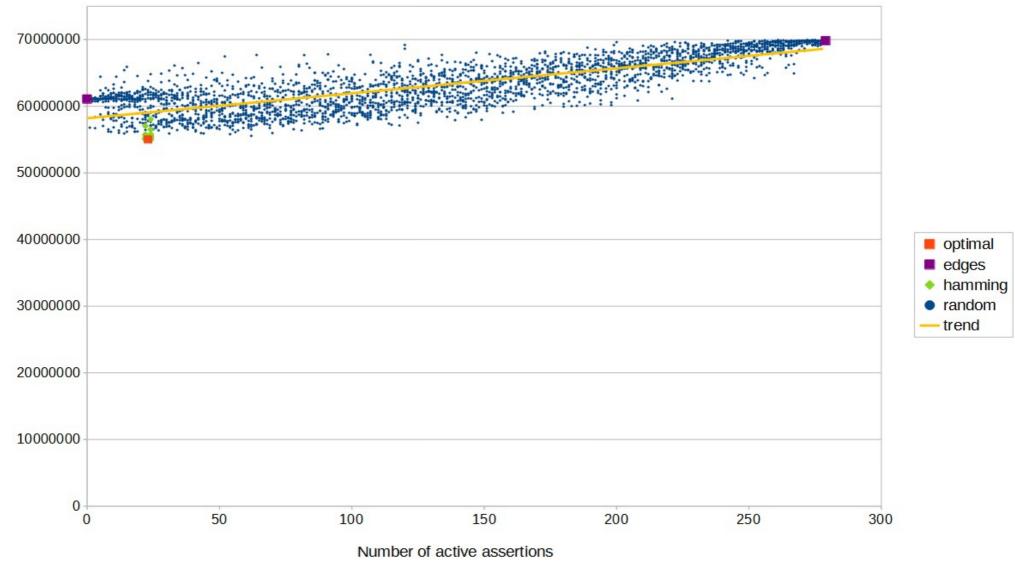
• eCos

- 4489 assertions
- Provided test suit
- Custom test with various kernel functions
- Up to 279 assertions executed

• Focus on eCos due to significantly more assertions



eCos custom test



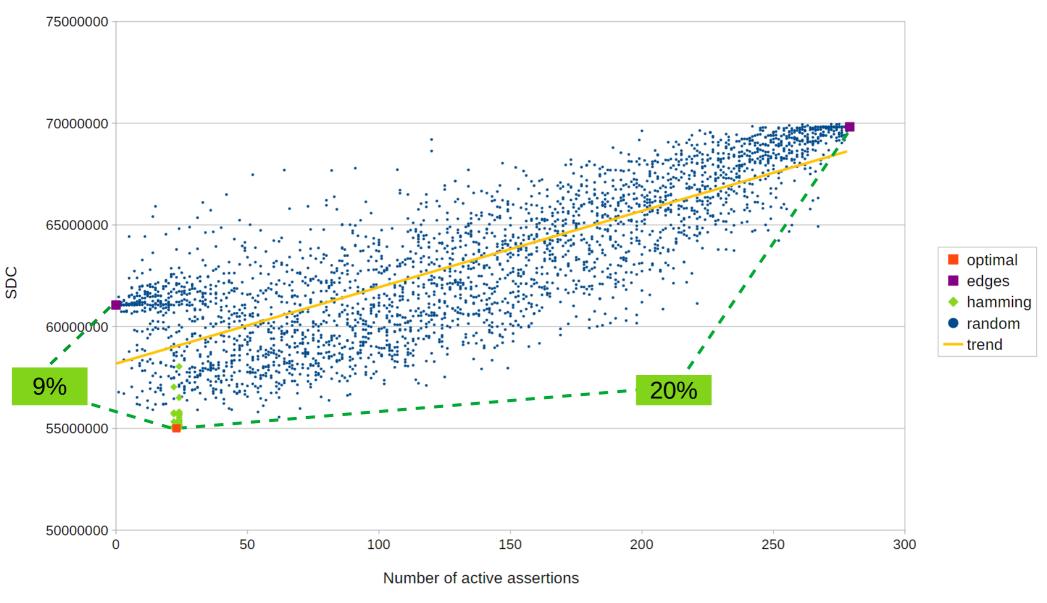
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SDC

Evaluation

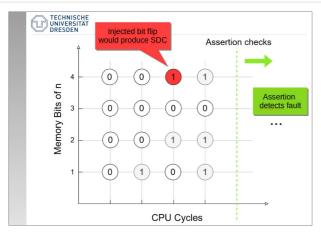


eCos custom test

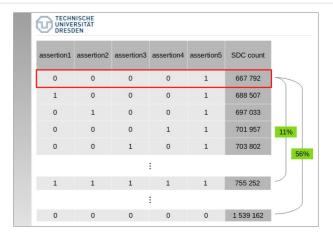


Evaluation



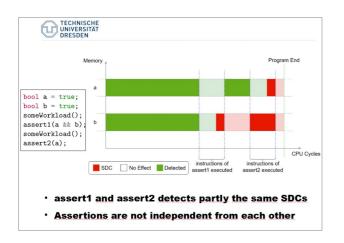


Assertions can detect faults



Only certain assertions good for fault tolerance

Key Takeaways



a SDC_{detected} SDC_{added} b SDCassertion-inactive = SDCall-assertions-active + SDCdetected - SDCadded

Finding an Optimal Configuration

campaign with all assertions active

Executing all 2^N configurations practically not possible
 Calculate SDCs of configuration from fault injection

Program End

- Runtime of assertion increases attack surface
- Assertions are dependent on each other

- Configurations can be calculated
- → ILP can be created

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